

Control Systems Questions and Answers – Linear Approximation of the Non-Linear System

This set of Control Systems Multiple Choice Questions & Answers (MCQs) focuses on "Linear Approximation of the Nonlinear System".

1. Due to which of the following reasons excessive band width in control systems should be avoided?

- a) It leads to slow speed of response
- b) It leads to low relative stability
- c) Noise is proportional to bandwidth
- d) Presence of feedback

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Answer: c

Explanation: Excessive Bandwidth causes increases in the noise with the same proportion as the bandwidth and hence noise is not good for any signal therefore the excessive bandwidth is not desirable.

2. In a stable control system backlash can cause which of the following?

- a) Underdamping
- b) Overdamping
- c) Poor stability at reduced values of open loop gain
- d) Low-level oscillations

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Answer: d

Explanation: In stable control systems backlash is the form of the error which may cause low level of the oscillations and hence can be useful sometimes as it increases the damping.

3. In an automatic control system which of the following elements is not used?

- a) Error detector
- b) Final control element
- c) Sensor
- d) Oscillator

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Answer: d

Explanation: In an automatic control system oscillator is not used because the oscillator increases the oscillations but our aim is to reduce the oscillations and hence oscillator is not used.

4. In a control system the output of the controller is given to

- a) Final control element
- b) Amplifier
- c) Comparator
- d) Sensor

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Answer: a

Explanation: In control system the output of the controller is given to the final control element it may be the plant or any other controller which-ever is used in the control circuit.

5. A controller, essentially, is a

- a) Sensor
- b) Clipper
- c) Comparator
- d) Amplifier

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Answer: c

Explanation: A controller is essentially the comparator which compares the given input with the reference input and generates the error signal.

6. Which of the following is the input to a controller?

- a) Servo signal
- b) Desired variable value

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Mike Jess



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