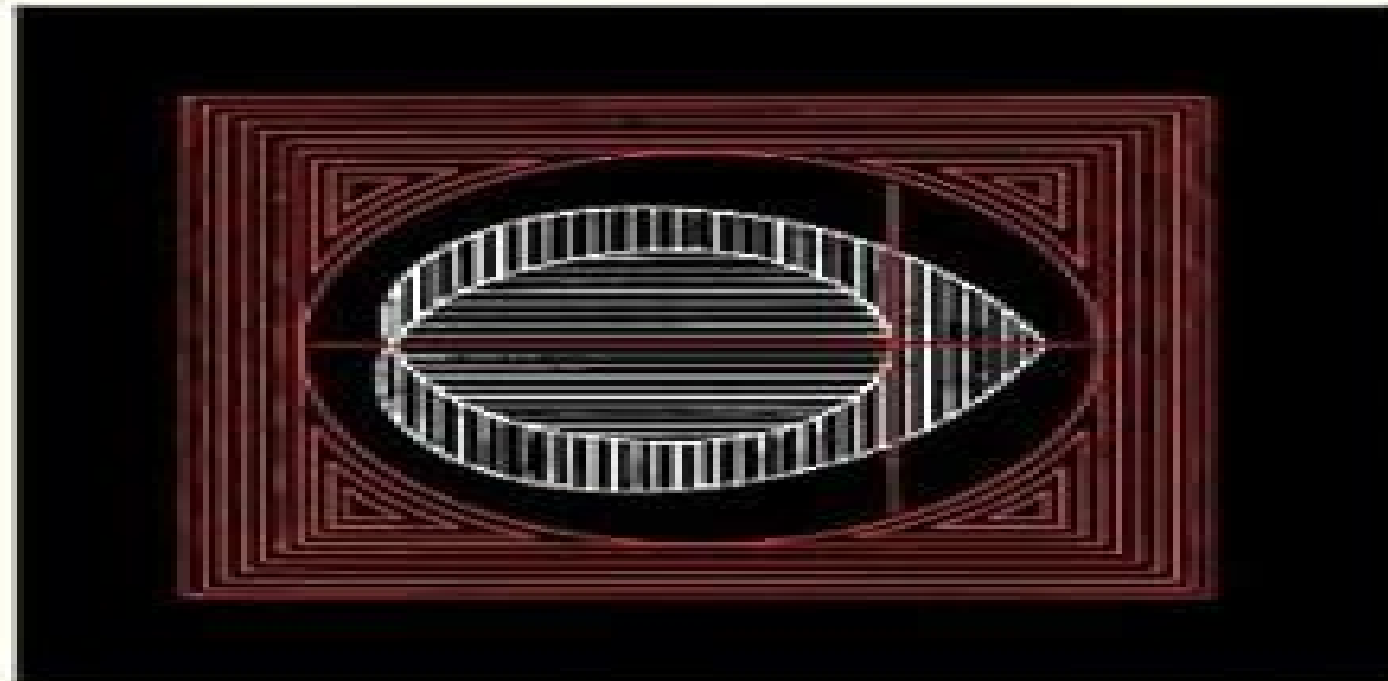# Frequency Domain Criteria for Absolute Stability

Kumpati S. Narendra/James H. Taylor

Frequency Domain Criteria For Absolute Stability Electrical Science

Jessica J Manson

Frequency Domain Criteria For Absolute Stability Electrical Science:

    Frequency Domain Criteria for Absolute stability Kumpati S. Narendra,2014-01-16 Frequency Domain Criteria for Absolute Stability presents some generalizations of the well known Popov solution to the absolute stability problem proposed by Lur e and Postnikov in 1944 This book is divided into nine chapters that focus on the application of Lyapunov s direct method to generate frequency domain criteria for stability The first eight chapters explore the systems with a single nonlinear function or time varying parameter These chapters also discuss the development of stability criteria for these systems the sufficiency theorems and Lyapunov function Some of the theorems applied to a damped version of the Mathieu equation and to a nonlinear equation derived from it are also covered The concluding chapter deals with systems with multiple nonlinearities or time varying gains This chapter also outlines the basic definitions and tools as well as the derivation of stability criteria This work will serve as a reference for research courses concerning stability problems related to the absolute stability problem of Lur e and Postnikov Engineers and applied mathematicians will also find this book invaluable   **Frequency Domain Criteria for Absolute Stability [by] Kumpati S. Narendra [and] James H. Taylor** Kumpati S. Narendra,1973   *Frequency Domain Criteria for Absolute Stability* Dmitry Altshuller,2012-07-25 Frequency Domain Criteria for Absolute Stability focuses on recently developed methods of delay integral quadratic constraints to provide criteria for absolute stability of nonlinear control systems The known or assumed properties of the system are the basis from which stability criteria are developed Through these methods many classical results are naturally extended particularly to time periodic but also to nonstationary systems Mathematical prerequisites including Lebesgue Stieltjes measures and integration are first explained in an informal style with technically more difficult proofs presented in separate sections that can be omitted without loss of continuity The results are presented in the frequency domain the form in which they naturally tend to arise In some cases the frequency domain criteria can be converted into computationally tractable linear matrix inequalities but in others especially those with a certain geometric interpretation inferences concerning stability can be made directly from the frequency domain inequalities The book is intended for applied mathematicians and control systems theorists It can also be of considerable use to mathematically minded engineers working with nonlinear systems   **World Congress of Nonlinear Analysts '92** V. Lakshmikantham,2011-11-14 No detailed description available for World Congress of Nonlinear Analysts 92   European Control Conference 1995 ,1995-09-05 Proceedings of the European Control Conference 1995 Rome Italy 5 8 September 1995   *Linear Matrix Inequalities in System and Control Theory* Stephen Boyd,Laurent El Ghaoui,Eric Feron,Venkataramanan Balakrishnan,1994-01-01 In this book the authors reduce a wide variety of problems arising in system and control theory to a handful of convex and quasiconvex optimization problems that involve linear matrix inequalities These optimization problems can be solved using recently developed numerical algorithms that not only are polynomial time but also work very well in practice the reduction therefore can be

considered a solution to the original problems This book opens up an important new research area in which convex optimization is combined with system and control theory resulting in the solution of a large number of previously unsolved problems   Stability Analysis and Design for Nonlinear Singular Systems Chunyu Yang,Qingling Zhang,Linna Zhou,2012-08-14 Singular systems which are also referred to as descriptor systems semi state systems differential algebraic systems or generalized state space systems have attracted much attention because of their extensive applications in the Leontief dynamic model electrical and mechanical models etc This monograph presented up to date research developments and references on stability analysis and design of nonlinear singular systems It investigated the problems of practical stability strongly absolute stability input state stability and observer design for nonlinear singular systems and the problems of absolute stability and multi objective control for nonlinear singularly perturbed systems by using Lyapunov stability theory comparison principle S procedure and linear matrix inequality LMI etc Practical stability being quite different from stability in the sense of Lyapunov is a significant performance specification from an engineering point of view The basic concepts and results on practical stability for standard state space systems were generalized to singular systems For Lur e type descriptor systems LDS which were the feedback interconnection of a descriptor system with a static nonlinearity strongly absolute stability was defined and Circle criterion and Popov criterion were derived The notion of input state stability ISS for nonlinear singular systems was defined based on the concept of ISS for standard state space systems and the characteristics of singular systems LMI based sufficient conditions for ISS of Lur e singular systems were proposed Furthermore observer design for nonlinear singular systems was studied and some observer design methods were proposed by the obtained stability results and convex optimization algorithms Finally absolute stability and multi objective control of nonlinear singularly perturbed systems were considered By Lyapunov functions absolute stability criteria of Lur e singularly perturbed systems were proposed and multi objective control of T S fuzzy singularly perturbed systems was achieved Compared with the existing results the obtained methods do not depend on the decomposition of the original system and can produce a determinate upper bound for the singular perturbation parameter   **AIAA Guidance Navigation and Control Conference** ,1996   *Proceedings of the Princeton Conference on Information Sciences and Systems* ,1971   Stability of Stationary Sets in Control Systems with Discontinuous Nonlinearities Vladimir Andreevich I?A?kubovich,Arkadi? Kha?movich Gelig,Gennadi? Alekseevich Leonov,2004 This book presents a development of the frequency domain approach to the stability study of stationary sets of systems with discontinuous nonlinearities The treatment is based on the theory of differential inclusions and the second Lyapunov method Various versions of the KalmanOCoYakubovich lemma on solvability of matrix inequalities are presented and discussed in detail It is shown how the tools developed can be applied to stability investigations of relay control systems gyroscopic systems mechanical systems with a Coulomb friction nonlinear electrical circuits cellular neural networks phase locked loops and synchronous machines Sample Chapter s Chapter 1 Foundations of

Theory of Differential Equations with Discontinuous Right Hand Sides 455 KB Contents Foundations of Theory of Differential Equations with Discontinuous Right Hand Sides Auxiliary Algebraic Statements on Solutions of Matrix Inequalities of a Special Type Dichotomy and Stability of Nonlinear Systems with Multiple Equilibria Stability of Equilibria Sets of Pendulum Like Systems Readership Upper level undergraduates graduate students academics researchers and engineers involved with mechanics electrical science and power systems <u>Proceedings of the ... Annual Princeton Conference on Information Sciences and Systems</u> Princeton Conference Dept. on Information Sciences and Systems, **Analysis and Control of Nonlinear Systems with Stationary Sets** Jinzhi Wang,2009 Nonlinear systems with stationary sets are important because they cover a lot of practical systems in engineering Previous analysis has been based on the frequency domain for this class of systems However few results on robustness analysis and controller design for these systems are easily available This book presents the analysis as well as methods based on the global properties of systems with stationary sets in a unified time domain and frequency domain framework The focus is on multi input and multi output systems compared to previous publications which considered only single input and single output systems The control methods presented in this book will be valuable for research on nonlinear systems with stationary sets **Control Systems: Theory and Applications** GHOSH,2013 Control Systems Theory and Applications contains a comprehensive coverage of the subject ranging from conventional control to modern control including non linear control digital control systems and applications of fuzzy logic Emphasis has been laid on the pedagogical aspects of the subject *Frequency Methods in Oscillation Theory* G.A. Leonov,I.M. Burkin,A.I. Shepeljavyi,2012-12-06 This book is devoted to nonlocal theory of nonlinear oscillations The frequency methods of investigating problems of cycle existence in multidimensional analogues of Van der Pol equation in dynamical systems with cylindrical phase space and dynamical systems satisfying Routh Hurwitz generalized conditions are systematically presented here for the first time To solve these problems methods of Poincar map construction frequency methods synthesis of Lyapunov direct methods and bifurcation theory elements are applied V M Popov s method is employed for obtaining frequency criteria which estimate period of oscillations Also an approach to investigate the stability of cycles based on the ideas of Zhukovsky Borg Hartmann and Olech is presented and the effects appearing when bounded trajectories are unstable are discussed For chaotic oscillations theorems on localizations of attractors are given The upper estimates of Hausdorff measure and dimension of attractors generalizing Doudy Oesterle and Smith theorems are obtained illustrated by the example of a Lorenz system and its different generalizations The analytical apparatus developed in the book is applied to the analysis of oscillation of various control systems pendulum like systems and those of synchronization Audience This volume will be of interest to those whose work involves Fourier analysis global analysis and analysis on manifolds as well as mathematics of physics and mechanics in general A background in linear algebra and differential equations is assumed **Stability Domains** Lyubomir T. Gruyitch,Jean-Pierre Richard,Pierre Borne,Jean-Claude Gentina,2003-12-15 Stability

Domains is an up to date account of stability theory with particular emphasis on stability domains Beyond the fundamental basis of the theory of dynamical systems it includes recent developments in the classical Lyapunov stability concept practical stabiliy properties and a new Lyapunov methodology for nonlinear systems It also introduces classical Lyapunov and practical stability theory for time invariant nonlinear systems in general and for complex interconnected large scale nonlinear dynamical systems in particular This is a complete treatment of the theory of stability domains useful for postgraduates and researchers working in this area of applied mathematics and engineering **Nonlinear Systems** ,2018-07-18 This book focuses on several key aspects of nonlinear systems including dynamic modeling state estimation and stability analysis It is intended to provide a wide range of readers in applied mathematics and various engineering disciplines an excellent survey of recent studies of nonlinear systems With its thirteen chapters the book brings together important contributions from renowned international researchers to provide an excellent survey of recent studies of nonlinear systems The first section consists of eight chapters that focus on nonlinear dynamic modeling and analysis techniques while the next section is composed of five chapters that center on state estimation methods and stability analysis for nonlinear systems Memoirs of the Faculty of Engineering and Design, Kyoto Institute of Technology ,1997 **Scientific and Technical Aerospace Reports** ,1995 **Revue roumaine des sciences techniques** ,1973 Monographic Series Library of Congress,1974

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