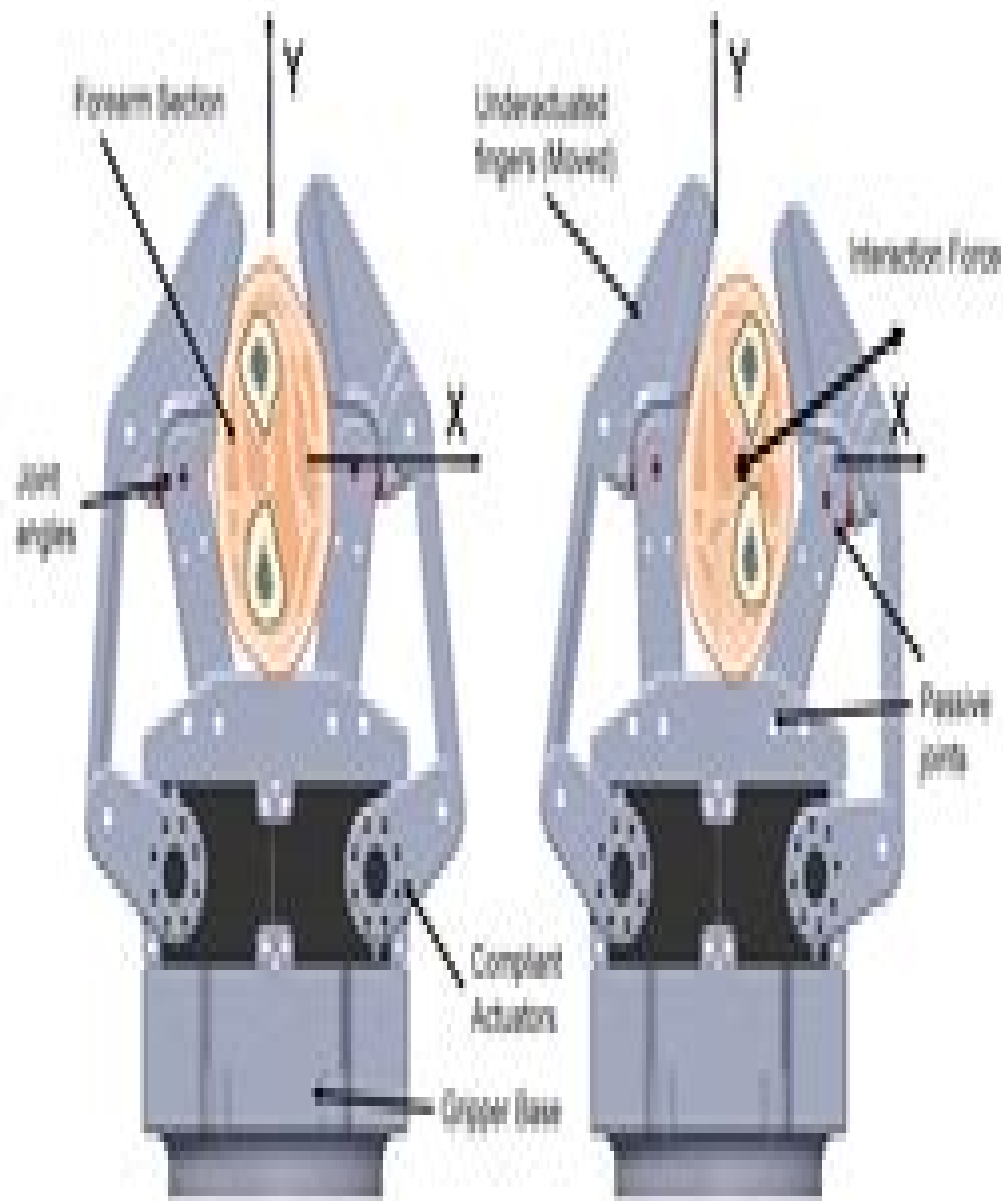




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(b)

# Control Design And Analysis For Underactuated Robotic Systems

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