

AUSTRALIA AND NEW ZEALAND EDITION

ENGINEERING MECHANICS  
**STATICS**

J. L. MERIAM  
L. G. KRAIGE  
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9th Edition



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# Engineering Mechanics Statics By J L Meriam 2012 05 11

**A Gutmann**



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discussed in detail and supported by numerous figures and tables

### **Principles of Soilscape and Landscape Evolution**

Garry Willgoose, 2018-03-01 Computational models are invaluable in understanding the complex effects of physical processes and environmental factors which interact to influence landform evolution of geologic time scales This book provides a holistic guide to the construction of numerical models to explain the co evolution of landforms soil vegetation and tectonics and describes how the geomorphology observable today has been formed It explains the science of the physical processes and the mechanics of how to solve them providing a useful resource for graduates studying geomorphology and sedimentary and erosion processes It also emphasises the methods for assessing the relative importance of different factors at field sites enabling researchers to select the appropriate processes to model Integrating a discussion of the fundamental processes with mathematical formulations it guides the reader in understanding which processes are important and why and creates a framework through which to study the interaction of soils vegetation and landforms over time

### **Engineering Metrology for Pedestrian Falls Prevention and Protection**

In-Ju Kim, 2022-03-25 This book explains how to improve the validity reliability and repeatability of slip resistance assessments amongst a range of shoes floors and environments from an engineering metrology viewpoint covering theoretical and experimental aspects of slip resistance mechanics and mechanisms Pedestrian falls resulting from slips or falls are one of the foremost causes of fatal and non fatal injuries that limit people s functionality There have been prolonged efforts globally to identify and understand their main causes and reduce their frequency and severity This book deals with large volumes of information on tribological characteristics such as friction and wear behaviours of the shoes and floors and their interactive impacts on slip resistance performances Readers are introduced to theoretical concepts and models and collected evidence on slip resistance properties amongst a range of shoe and floor types and materials under various ambulatory settings These approaches can be used to develop secure design strategies against fall incidents and provide a great step forward to build safer shoes floors and walking working environments for industries and communities around the world The book includes many case studies

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Markus Grebenstein, 2014-01-24 Humanoid robotics have made remarkable progress since the dawn of robotics So why don t we have humanoid robot assistants in day to day life yet This book analyzes the keys to building a successful humanoid robot for field robotics where collisions become an unavoidable part of the game The author argues that the design goal should be real anthropomorphism as opposed to mere human like appearance He deduces three major characteristics to aim for when designing a humanoid robot particularly robot hands Robustness against impacts Fast dynamics Human like grasping and manipulation performance Instead of blindly copying human anatomy this book opts for a holistic design methodology It analyzes human hands and existing robot hands to elucidate the important functionalities that are the building blocks toward these necessary characteristics They are the keys to designing an anthropomorphic robot hand as illustrated in the high performance anthropomorphic Awiwi Hand presented in this book This is not only a handbook for robot hand designers It

gives a comprehensive survey and analysis of the state of the art in robot hands as well as the human anatomy It is also aimed at researchers and roboticists interested in the underlying functionalities of hands grasping and manipulation The methodology of functional abstraction is not limited to robot hands it can also help realize a new generation of humanoid robots to accommodate a broader spectrum of the needs of human society

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