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## CHAPTER 6

6.2-1. Consider the closed-loop system of Fig. P6.2-1.

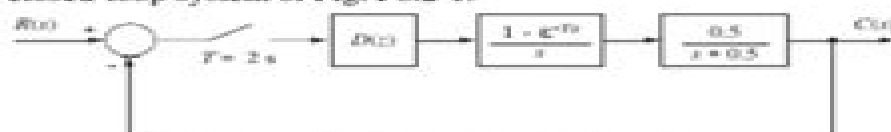


Figure P6.2-1 System for Problem 6.2-1.

- Calculate and plot the unit-step response at the sampling instants, for the case that  $D(z) = 1$ .
- Calculate the system unit-step response of the analog system, that is, with the sampler, digital controller, and data hold removed. Plot the response on the same graph with the results of part (a).
- For the system of Fig. P6.2-1, let  $D(z) = 1$  and  $T = 0.4$  s. Calculate the unit-step response and plot these results on the same graph used for parts (a) and (b).
- Use the system dc gains to calculate the steady-state responses for each of the systems of parts (a), (b), and (c). Why are these gains equal?

**Solution:**

$$(a) \quad G(z) = \left. \frac{z-1}{z} \right|_{\substack{\left[ \frac{0.5}{s(s+0.5)} \right] \\ \left[ \frac{1 - e^{-Ts}}{s} \right]}} = \frac{z-1}{z} \frac{(1 - e^{-T})}{(z-1)(z - e^{-T})} = \frac{0.6321}{z - 0.3679}$$

$$\frac{G(z)}{1 + G(z)} = \frac{0.6321}{z - 0.2642}$$

$$\frac{C(z)}{z} = \frac{0.6321}{z - 0.2642} = \frac{0.5}{z} + \frac{-0.5}{z - 0.2642}$$

# Digital Control System Analysis And Design Solution

**Padhraic Smyth**



## **Digital Control System Analysis And Design Solution:**

*Digital Control System Analysis and Design* Charles L. Phillips, H. Troy Nagle, 1990      Linear Control System Analysis and Design Constantine H. Houpis, Stuart N. Sheldon, John J. D'Azzo, 2003-08-14 Thoroughly classroom tested and proven to be a valuable self study companion Linear Control System Analysis and Design Fifth Edition uses in depth explanations diagrams calculations and tables to provide an intensive overview of modern control theory and conventional control system design The authors keep the mathematics to a minimum while stressing real world engineering challenges Completely updated and packed with student friendly features the Fifth Edition presents a wide range of examples using MATLAB and TOTAL PC as well as an appendix listing MATLAB functions for optimizing control system analysis and design Eighty percent of the problems presented in the previous edition have been revised to further reinforce concepts necessary for current electrical aeronautical astronautical and mechanical applications      **Linear Control System Analysis and Design with MATLAB®, Sixth Edition** Constantine H. Houpis, Stuart N. Sheldon, 2013-10-30 Thoroughly classroom tested and proven to be a valuable self study companion Linear Control System Analysis and Design Sixth Edition provides an intensive overview of modern control theory and conventional control system design using in depth explanations diagrams calculations and tables Keeping mathematics to a minimum the book is designed with the undergraduate in mind first building a foundation then bridging the gap between control theory and its real world application Computer aided design accuracy checks CADAC are used throughout the text to enhance computer literacy Each CADAC uses fundamental concepts to ensure the viability of a computer solution Completely updated and packed with student friendly features the sixth edition presents a range of updated examples using MATLAB as well as an appendix listing MATLAB functions for optimizing control system analysis and design Over 75 percent of the problems presented in the previous edition have been revised or replaced      **Introduction to Digital Control** Biswanath Samanta, 2024-10-17 This textbook presents an integrated approach to digital discrete time control systems covering analysis design simulation and real time implementation through relevant hardware and software platforms Topics related to discrete time control systems include z transform inverse z transform sampling and reconstruction open and closed loop system characteristics steady state accuracy for different system types and input functions stability analysis in z domain Jury's test bilinear transformation from z to w domain stability analysis in w domain Routh Hurwitz criterion root locus techniques in z domain frequency domain analysis in w domain control system specifications in time and frequency domains design of controllers PI PD PID phase lag phase lead phase lag lead using time and frequency domain specifications state space methods controllability and observability pole placement controllers design of observers estimators full order prediction reduced order and current observers system identification optimal control linear quadratic regulator LQR linear quadratic Gaussian LQG estimator Kalman filter implementation of controllers and laboratory experiments for validation of analysis and design techniques on real laboratory scale hardware modules Both single input

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proceedings of the IFAC Symposium held at New Delhi India on January 5 7 1982 This book particularly presents the texts of the five plenary talks and the 110 papers of the symposium This book organizes the papers into 109 chapters with nearly one third of the papers focus on digital control particularly software and hardware of control using microcomputers computer aided design and adaptive control and modeling for digital control Another set of papers deal with several applications of digital control techniques in solving interesting problems of socio economic systems electrical power systems bio systems and artificial satellites The reader will benefit hugely from the topics in this book that span several important theoretical and applied areas of the fast changing topic of digital control

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with emphasis on engineering design Fadali and Visioli cover analysis and design of digitally controlled systems and describe applications of digital control in a wide range of fields With worked examples and Matlab applications in every chapter and many end of chapter assignments this text provides both theory and practice for those coming to digital control engineering for the first time whether as a student or practicing engineer This new edition covers new topics such as Model Predictive Control and Linear Matrix Inequalities To engage students it has more illustrations and simple examples the mathematical notation is reduced where possible and it also includes intermediate mathematical steps in derivations Companion website features resources for instructors including Powerpoint slides and solutions Extensive use of CAD Packages Matlab and Simulink sections at the end of each chapter show how to implement concepts from the chapter Contains review material to aid understanding of digital control analysis and design Includes some advanced material to make it suitable for an introductory graduate level class or for two quarters at the senior graduate level The mathematics background required for understanding most of the book is based on what can be reasonably expected from the average electrical chemical or mechanical engineering senior

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**Embedded Digital Control with Microcontrollers** Cem Unsalan, Duygun E. Barkana, H. Deniz

Gurhan, 2021-04-06 EMBEDDED DIGITAL CONTROL WITH MICROCONTROLLERS Explore a concise and practical introduction to implementation methods and the theory of digital control systems on microcontrollers Embedded Digital Control with Microcontrollers delivers expert instruction in digital control system implementation techniques on the widely used ARM Cortex M microcontroller The accomplished authors present the included information in three phases First they describe how to implement prototype digital control systems via the Python programming language in order to help the reader better understand theoretical digital control concepts Second the book offers readers direction on using the C programming language to implement digital control systems on actual microcontrollers This will allow readers to solve real

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**Digital Control Engineering** M. Sami Fadali, Antonio Visioli, 2012-09-06 Digital controllers are part of nearly all modern personal industrial and transportation systems Every senior or graduate student of electrical chemical or mechanical engineering should therefore be familiar with the basic theory of digital controllers This new text covers the fundamental principles and applications of digital control engineering with emphasis on engineering design Fadali and Visioli cover analysis and design of digitally controlled systems and describe applications of digital controls in a wide range of fields With worked examples and Matlab applications in every chapter and many end of chapter assignments this text provides both theory and practice for those coming to digital control engineering for the first time whether as a student or practicing engineer Extensive Use of computational tools Matlab sections at end of each chapter show how to implement concepts from the chapter Frees the student from the drudgery of mundane calculations and allows him to consider more subtle aspects of control system analysis and design An engineering approach to digital controls emphasis throughout the book is on design of control systems Mathematics is used to help explain concepts but throughout the text discussion is tied to design and implementation For example coverage of analog controls in chapter 5 is not simply a review but is used to show how analog control systems map to digital control systems Review of Background Material contains review material to aid understanding of digital control analysis and design Examples include discussion of discrete time systems in time domain and frequency domain reviewed from linear systems course and root locus design in s domain and z domain reviewed from feedback control course Inclusion of Advanced Topics In addition to the basic topics required for a one semester senior graduate class the text includes some advanced material to make it suitable for an introductory graduate level class or for two quarters at the senior graduate level Examples of optional topics are state space methods which may receive brief coverage in a one semester course and nonlinear discrete time systems Minimal Mathematics Prerequisites The mathematics background required for

understanding most of the book is based on what can be reasonably expected from the average electrical chemical or mechanical engineering senior This background includes three semesters of calculus differential equations and basic linear algebra Some texts on digital control require more

**Modern Control System Theory and Design** Stanley M. Shinnars, 1998-05-06 The definitive guide to control system design Modern Control System Theory and Design Second Edition offers the most comprehensive treatment of control systems available today Its unique text software combination integrates classical and modern control system theories while promoting an interactive computer based approach to design solutions The sheer volume of practical examples as well as the hundreds of illustrations of control systems from all engineering fields make this volume accessible to students and indispensable for professional engineers This fully updated Second Edition features a new chapter on modern control system design including state space design techniques Ackermann's formula for pole placement estimation robust control and the H method for control system design Other notable additions to this edition are Free MATLAB software containing problem solutions which can be retrieved from The Mathworks Inc anonymous FTP server at <ftp://ftp.mathworks.com/pub/books/shinnars> Programs and tutorials on the use of MATLAB incorporated directly into the text A complete set of working digital computer programs Reviews of commercial software packages for control system analysis An extensive set of new worked out illustrative solutions added in dedicated sections at the end of chapters Expanded end of chapter problems one third with answers to facilitate self study An updated solutions manual containing solutions to the remaining two thirds of the problems Superbly organized and easy to use Modern Control System Theory and Design Second Edition is an ideal textbook for introductory courses in control systems and an excellent professional reference Its interdisciplinary approach makes it invaluable for practicing engineers in electrical mechanical aeronautical chemical and nuclear engineering and related areas

**Advances in Unmanned Marine Vehicles** G.N. Roberts, R. Sutton, 2006-01-31 Unmanned marine vehicles UMVs include autonomous underwater vehicles remotely operated vehicles semi submersibles and unmanned surface craft Considerable importance is being placed on the design and development of such vehicles as they provide cost effective solutions to a number of littoral coastal and offshore problems This book highlights the advanced technology that is evolving to meet the challenges being posed in this exciting and growing area of research

*Computer Aided Design in Control and Engineering Systems* P. Martin Larsen, N. E. Hansen, 2014-05-17 Computer Aided Design in Control and Engineering Systems contains the proceedings of the 3rd International Federation of Automatic Control International Federation for Information Processing Symposium held in Lyngby Denmark from July 31 to August 2 1985 The papers review the state of the art and the trends in development of computer aided design CAD of control and engineering systems techniques procedures and concepts This book is comprised of 74 chapters divided into 17 sections and begins with a description of a prototype computer environment that combines expert control system analysis and design tools The discussion then turns to decision support systems which could be used to



address problems of management and control of large scale multiproduct multiline batch manufacturing outside the mechanical engineering industries The following chapters focus on the use of CAD in control education industrial applications of CAD and hardware software systems Some examples of universal and specialized CAD packages are presented and applications of CAD in electric power plants process control systems and transportation systems are highlighted The remaining chapters look at CAD computer aided engineering computer aided manufacturing systems as well as the use of mathematical methods in CAD This monograph will be of interest to practitioners in computer science computer engineering and industrial engineering

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