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From Living Eyes To Seeing Machines

James Trefil



From Living Eyes To Seeing Machines:

Bio-inspired Flying Robots Jean-Christophe Zufferey, 2008-04-24 This book demonstrates how bio inspiration can lead to fully autonomous flying robots without relying on external aids Most existing aerial robots fly in open skies far from obstacles and rely on external beacons mainly GPS to localise and navigate However these robots are not able to fly at low altitude or in confined environments and yet this poses absolutely no difficulty to insects Indeed flying insects display efficient flight control capabilities in complex environments despite their limited weight and relatively tiny brain size From sensor suite to control strategies the literature on flying insects is reviewed from an engineering perspective in order to extract useful principles that are then applied to the synthesis of artificial indoor flyers Artificial evolution is also utilised to search for alternative control systems and behaviors that match the constraints of small flying robots Specifically the basic sensory modalities of insects vision gyroscopes and airflow sense are applied to develop navigation controllers for indoor flying robots These robots are capable of mapping sensor information onto actuator commands in real time to maintain altitude stabilize the course and avoid obstacles The most prominent result of this novel approach is a 10 gram microflyer capable of fully autonomous operation in an office sized room using fly inspired vision inertial and airspeed sensors This book is intended for all those interested in autonomous robotics in academia and industry

Motion Vision Johannes M. Zanker, Jochen Zeil, 2011-06-28 In six parts this book considers the extent to which computational neural and ecological constraints have shaped the mechanisms underlying motion vision Early Motion Vision Motion Signals for Local and Global Analysis Optical Flow Patterns Motion Vision in Action Neural Coding of Motion Motion in Natural Environments Each topic is introduced by a keynote chapter which is accompanied by several companion articles Written by an international group of experts in neurobiology psychophysics animal behaviour machine vision and robotics the book is designed to explore as comprehensively as possible the present state of knowledge concerning the principal factors that have guided the evolution of motion vision

Sensors and Sensing in Biology and Engineering Friedrich G. Barth, Joseph A.C. Humphrey, Timothy W. Secomb, 2012-12-06 Biological sensors are usually remarkably small sensitive and efficient It is highly desirable to design corresponding artificial sensors for scientific industrial and commercial purposes This book is designed to fill an urgent need for interdisciplinary exchange between biologists studying sensors in the natural world and engineers and physical scientists developing artificial sensors Contributions from leading scientists in this area whether engineers or biologists are written to be accessible to readers from these and other disciplines The main topics cover mechanical sensors visual sensors and vision and chemosensors Readers will obtain a fuller understanding of the nature and performance of natural sensors as well as enhanced appreciation for the current status and the potential applicability of artificial microsensors Friedrich G Barth was awarded the Karl Ritter von Frisch Medaille at the 2003 Annual Conference of the German Zoological Society in Halle Germany

Travelling Facts Caroline Baillie, Elizabeth C. Dunn, 2004 Travelling Facts explores the production and

distribution of facts their life cycles as well as the material networks through which they travel Acknowledging that facts are fallible and originate primarily in isolated laboratories and field sites the volume includes discussions about how facts are reassembled into practical knowledge how they translate locally and what lessons may be learned from those who attempt to regulate fact production and circulation in the face of the marked acceleration and expansion of digital technologies worldwide

From Animals to Animats 5 Rolf Pfeifer,1998 The Animals to Animats Conference brings together researchers from ethology psychology ecology artificial intelligence artificial life robotics engineering and related fields to further understanding of the behaviors and underlying mechanisms that allow natural and synthetic agents animats to adapt and survive in uncertain environments The Animals to Animats Conference brings together researchers from ethology psychology ecology artificial intelligence artificial life robotics engineering and related fields to further understanding of the behaviors and underlying mechanisms that allow natural and synthetic agents animats to adapt and survive in uncertain environments The work presented focuses on well defined models robotic computer simulation and mathematical that help to characterize and compare various organizational principles or architectures underlying adaptive behavior in both natural animals and animats **From Animals to Animats 7** Bridget Hallam,Dario Floreano,John Hallam,Gillian M.

Hayes,Jean-Arcady Meyer,2002 Proceedings of the Seventh International Conference on Simulation of Adaptive Behavior

Neuronal Processing of Optic Flow ,1999-12-06 When we walk drive a car or fly an airplane visual motion is used to control and guide our movement Optic flow describes the characteristic pattern of visual motion that arises in these situations This book is the first to take an in depth look at the neuronal processing strategies that underlie the brain's ability to analyze and use optic flow for the control of self motion It does so in a variety of species which use optic flow in different behavioral contexts The spectrum ranges from flying insects to birds higher mammals and man The contributions cover physiological and behavioral studies as well as computational models Neuronal Processing of Optic Flow provides an authoritative and comprehensive overview of the current state of research on this topic written by a group of authors who have made essential contributions to shaping this field of research over the last ten years Provides the first detailed overview of the analysis of complex visual motion patterns in the brain Includes physiological behavioral and computational aspects of optic flow processing Highlights similarities and differences between different animal species and behavioral tasks Covers human patients with visual motion deficits Enhances the reader's understanding with many illustrations *Artificial Neural Networks — ICANN 2002* Jose R. Dorronsoro,2002-08-14 The International Conferences on Artificial Neural Networks ICANN have been held annually since 1991 and over the years have become the major European meeting in neural networks This proceedings volume contains all the papers presented at ICANN 2002 the 12th ICANN conference held in August 28-30 2002 at the Escuela Técnica Superior de Informática of the Universidad Autónoma de Madrid and organized by its Neural Networks group ICANN 2002 received a very high number of contributions more than 450 Almost all papers were revised by

three independent reviewers selected among the more than 240 serving at this year's ICANN and 221 papers were finally selected for publication in these proceedings due to space considerations quite a few good contributions had to be left out. I would like to thank the Program Committee and all the reviewers for the great collective effort and for helping us to have a high quality conference.

Imaging Beyond the Pinhole Camera Kostas Daniilidis, Reinhard Klette, 2006-09-21 This book traces progress in photography since the first pinhole or camera obscura architecture. The authors describe innovations such as photogrammetry and omnidirectional vision for robotic navigation. The text shows how new camera architectures create a need to master related projective geometries for calibration, binocular stereo, static or dynamic scene understanding. Written by leading researchers in the field, this book also explores applications of alternative camera architectures.

Artificial Evolution Jin-Kao Hao, 1998-02-18 The volume presents a survey of the state of the art in artificial evolution covering theoretical issues, methodologies, and applications in various areas including genetic algorithm operators and evolvable hardware and robotics.

Optic Flow and Beyond L.M. Vaina, Scott A. Beardsley, Simon K. Rushton, 2004-04-30 Optic flow provides all the information necessary to guide a walking human or a mobile robot to its target. Over the past 50 years a body of research on optic flow spanning the disciplines of neurophysiology, psychophysics, experimental psychology, brain imaging, and computational modelling has accumulated. Today when we survey the field we find independent lines of research have now converged and many arguments have been resolved simultaneously; the underpinning assumptions of flow theory are being questioned and alternative accounts of the visual guidance of locomotion proposed. At this critical juncture this volume offers a timely review of what has been learnt and pointers to where the field is going.

Advances in Robot Learning Jeremy Wyatt, John Demiris, 2003-06-29 This book constitutes the thoroughly refereed post-workshop proceedings of the 8th European Workshop on Learning Robots (EWLR 99) held in Lausanne, Switzerland, in September 1999. The seven revised full workshop papers presented were carefully reviewed and selected for inclusion in the book. Also included are two invited full papers. Among the topics addressed are map building for robot navigation, multi-task reinforcement learning, neural network approaches, example-based learning, situated agents, planning maps for mobile robots, path finding, autonomous robots, and biologically inspired approaches.

From Animals to Animats 4 Pattie Maes, 1996 From Animals to Animats 4 brings together the latest research at the frontier of an exciting new approach to understanding intelligence.

Neurotechnology for Biomimetic Robots Joseph Ayers, Joel L. Davis, Alan Rudolph, 2002 An overview of neurotechnology: the engineering of robots based on animals and animal behavior. The goal of neurotechnology is to confer the performance advantages of animal systems on robotic machines. Biomimetic robots differ from traditional robots in that they are agile, relatively cheap, and able to deal with real-world environments. The engineering of these robots requires a thorough understanding of the biological systems on which they are based at both the biomechanical and physiological levels. This book provides an in-depth overview of the field. The areas covered include myomorphic actuators which mimic muscle action, neuromorphic sensors which like

animal sensors represent sensory modalities such as light pressure and motion in a labeled line code biomimetic controllers based on the relatively simple control systems of invertebrate animals and the autonomous behaviors that are based on an animal's selection of behaviors from a species specific behavioral library The ultimate goal is to develop a truly autonomous robot one able to navigate and interact with its environment solely on the basis of sensory feedback without prompting from a human operator *Cephalopod Cognition* Anne-Sophie Darmaillacq, Ludovic Dickel, Jennifer Mather, 2014-07-10

Cephalopods are generally regarded as the most intelligent group among the invertebrates Despite their popularity relatively little is known about the range and function of their cognitive abilities This book fills that gap accentuating the varied and fascinating aspects of cognition across the group Starting with the brain learning and memory Part I looks at early learning memory acquisition and cognitive development in modern cephalopods An analysis of the chambered nautilus a living fossil is included providing insight into the evolution of behavioural complexity Part II surveys environmental responses especially within the active and learning dependent coleoids The ever intriguing camouflage abilities of octopus and cuttlefish are highlighted alongside bioluminescence navigation and other aspects of visual and cognitive competence Covering the range of cognitive function this text underscores the importance of the cephalopods within the field of comparative cognition generally It will be highly valuable for researchers graduates and senior undergraduate students *Fourth European*

Conference on Artificial Life Phil Husbands, Inman Harvey, 1997 Topics include self organization the origins of life natural selection evolutionary computation neural networks communication artificial worlds software agents philosophical issues in artificial life ethical problems and learning and development Researchers in artificial life attempt to use the physical representation of lifelike phenomena to understand the organizational principles underlying the dynamics of living systems The goal of the 1997 European Conference on Artificial Life is to provoke new understandings of the relationships between the natural and the artificial Topics include self organization the origins of life natural selection evolutionary computation neural networks communication artificial worlds software agents philosophical issues in artificial life ethical problems and learning and development Time-to-Contact Heiko Hecht, Geert Savelsbergh, 2004-05-06 Time to contact is the visual

information that observers use in fundamental tasks such as landing an airplane or hitting a ball Time to contact has been a hot topic in perception and action for many years and although many articles have been published on this topic a comprehensive overview or assessment of the theory does not yet exist This book fills an important gap and will have appeal to the perception and action community The book is divided into four sections Section one covers the foundation of time to contact Section two covers different behavioral approaches to time to contact estimation Section three focuses on time to contact as perception and strategy and Section four covers time to contact and action regulation **Experimental**

Robotics VI Peter I. Corke, James Trevelyan, 1999-10-22 This book presents the proceedings of the 6th International Symposium on Experimental Robotics held in Sydney in March 1999 The editors and contributors represent the leading

robotics research efforts from around the world Micro machines interplanetary exploration minimally invasive surgery and emerging humanoid robots are among the most obvious attainments of leading robotics research teams reported in this volume Less obvious but equally significant are the fundamental advances in robot map building and methods of communication between humans and machines that are demonstrated through experimental results This collection of papers will provide the reader with a concise report on the current achievements and future trends in robotics research across the world

Evolutionary Design by Computers Peter Bentley, 1999-05-28 Evolutionary Design By Computers offers an enticing preview of the future of computer aided design Design by Darwin Lawrence J Fogel President Natural Selection Inc Evolutionary design by computers is the major revolution in design thinking of the 20th century and this book is the best introduction available Professor John Frazer Swire Chair and Head of School of Design the Hong Kong Polytechnic University Author of An Evolutionary Architecture Peter Bentley has assembled and edited an important collection of papers that demonstrate convincingly the utility of evolutionary computation for engineering solutions to complex problems in design David B Fogel Editor in Chief IEEE Transactions on Evolutionary Computation Some of the most startling achievements in the use of computers to automate design are being accomplished by the use of evolutionary search algorithms to evolve designs Evolutionary Design By Computers provides a showcase of the best and most original work of the leading international experts in Evolutionary Computation Engineering Design Computer Art and Artificial Life By bringing together the highest achievers in these fields for the first time including a foreword by Richard Dawkins this book provides the definitive coverage of significant developments in Evolutionary Design This book explores related sub areas of Evolutionary Design including design optimization creative design the creation of art artificial life It shows for the first time how techniques in each area overlap and promotes the cross fertilization of ideas and methods

The Encyclopedia of Science and Technology James Trefil, 2001-08-24 Edited by acclaimed science writer and physicist James Trefil the Encyclopedia s 1000 entries combine in depth coverage with a vivid graphic format to bring every facet of science technology and medicine into stunning focus From absolute zero to the Mesozoic era to semiconductors to the twin paradox Trefil and his co authors have an uncanny ability to convey how the universe works and to show readers how to apply that knowledge to everyday problems

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