Cooperative Control of Multi-Agent Systems



Zhongkui Li - Zhisheng Duan



Cooperative Control Of Multi Agent Systems A Consensus Region Approach

Zhongkui Li, Zhisheng Duan

Cooperative Control Of Multi Agent Systems A Consensus Region Approach:

Cooperative Control of Multi-agent Systems Zhongkui Li, Zhisheng Duan, 2015 Distributed controller design is generally a challenging task especially for multi agent systems with complex dynamics due to the interconnected effect of the agent dynamics the interaction graph among agents and the cooperative control laws Cooperative Control of Multi Agent Systems A Consensus Region Approach offers a systematic framework for designing distributed controllers for multi agent systems with general linear agent dynamics linear agent dynamics with uncertainties and Lipschitz nonlinear agent dynamics

Cooperative Control of Multi-Agent Systems Zhongkui Li, Zhisheng Duan, 2017-12-19 Distributed controller design is generally a challenging task especially for multi agent systems with complex dynamics due to the interconnected effect of the agent dynamics the interaction graph among agents and the cooperative control laws Cooperative Control of Multi Agent Systems A Consensus Region Approach offers a systematic framework for designing distributed controllers for multi agent systems with general linear agent dynamics linear agent dynamics with uncertainties and Lipschitz nonlinear agent dynamics Beginning with an introduction to cooperative control and graph theory this monograph Explores the consensus control problem for continuous time and discrete time linear multi agent systems Studies the H and H2 consensus problems for linear multi agent systems subject to external disturbances Designs distributed adaptive consensus protocols for continuous time linear multi agent systems Considers the distributed tracking control problem for linear multi agent systems with a leader of nonzero control input Examines the distributed containment control problem for the case with multiple leaders Covers the robust cooperative control problem for multi agent systems with linear nominal agent dynamics subject to heterogeneous matching uncertainties Discusses the global consensus problem for Lipschitz nonlinear multi agent systems Cooperative Control of Multi Agent Systems A Consensus Region Approach provides a novel approach to designing distributed cooperative protocols for multi agent systems with complex dynamics The proposed consensus region decouples the design of the feedback gain matrices of the cooperative protocols from the communication graph and serves as a measure for the robustness of the protocols to variations of the communication graph By exploiting the decoupling feature adaptive cooperative protocols are presented that can be designed and implemented in a fully distributed fashion Cooperative **Control of Multi-Agent Systems** James Cooper, 2017-09-19 Cooperative Control of Multi Agent Systems provides a novel approach to designing distributed cooperative protocols for multi agent systems with complex dynamics The proposed consensus region decouples the design of the feedback gain matrices of the cooperative protocols from the communication graph and serves as a measure for the robustness of the protocols to variations of the communication graph By exploiting the decoupling feature adaptive cooperative protocols are presented that can be designed and implemented in a fully distributed fashion Robust Cooperative Control of Multi-Agent Systems Chunyan Wang, Zongyu Zuo, Jianan Wang, Zhengtao Ding, 2021-05-18 This book presents a concise introduction to the latest advances in robust cooperative control design for

multi agent systems with input delay and external disturbances especially from a prediction and observation perspective The volume covers a wide range of applications such as the trajectory tracking of quadrotors formation flying of multiple unmanned aerial vehicles UAVs and fixed time formation of ground vehicles Robust cooperative control means that multi agent systems are able to achieve specified control tasks while remaining robust in the face of both parametric and nonparametric model uncertainties In addition the authors cover a wide range of key issues in cooperative control such as communication and input delays parametric model uncertainties and external disturbances Moving beyond the scope of existing works a systematic prediction and observation approach to designing robust cooperative control laws is presented About the Authors Chunyan Wang is an Associate Professor in the School of Aerospace Engineering at Beijing Institute of Technology China Zongyu Zuo is a full Professor with the School of Automation Science and Electrical Engineering Beihang University China Jianan Wang is an Associate Professor in the School of Aerospace Engineering at Beijing Institute of Technology China Zhengtao Ding is a Professor in the Department of Electrical and Electronic Engineering at University of Manchester U K RETRACTED BOOK: Control Design of Multiagent Discrete-Time Systems MagdiSadek Mahmoud, Bilal J. Karaki, 2022-03-16 This book describes an effective approach to the cooperative and coordinated control of multivehicle systems This rigorous analytic approach guarantees the stability of coordinated and cooperating vehicles using distributed protocols and uses low energy event triggered mechanisms for networked vehicle control The text covers design of a cooperative protocol to achieve consensus for multivehicle systems allowing cooperation that is resistant to the effects of packet loss and or adversarial attack analysis and synthesis of an event triggering mechanism for cooperative multivehicle systems over uncertain networks and the problem of distributed leader following consensus and methods for compelling multivehicle systems to reach consensus Throughout the book cooperation problems are transformed into stability problems Lyapunov theory is used to guarantee cooperation among agents The distributed approach is applied to triggering mechanisms the cooperation process and the impact of cyber attacks Discrete time analysis shows how the event based structure can be designed to match the performance of continuous time counterparts The book details applications and computer simulation with several practical examples This book is of interest to a wide audience from the graduate student through the academic researcher to the industrial practitioner all of them sharing a common interest in the stability and security of multiagent systems Proceedings of 2021 5th Chinese Conference on Swarm Intelligence and Cooperative Control Zhang Ren, Mengyi Wang, Yongzhao Hua, 2022-07-29 This book includes original peer reviewed research papers from the 2021 5th Chinese Conference on Swarm Intelligence and Cooperative Control CCSICC2021 held in Shenzhen China on January 19 22 2022 The topics covered include but are not limited to reviews and discussions of swarm intelligence basic theories on swarm intelligence swarm communication and networking swarm perception awareness and location swarm decision and planning cooperative control cooperative guidance swarm simulation and assessment The papers showcased

here share the latest findings on theories algorithms and applications in swarm intelligence and cooperative control making the book a valuable asset for researchers engineers and university students alike *Consensus Problem of Delayed Linear Multi-agent Systems* Cheng-Lin Liu, Fei Liu, 2016-09-27 In the context of coupled coordination control mechanisms this book focuses on the delay robustness of consensus problems with asynchronously coupled and synchronously coupled consensus algorithms respectively Moreover constructive consensus algorithms that tolerate larger communication delays are proposed according to idea of compensation By providing rigorous theoretical proofs and numerous numerical simulations it enhances readers understanding of the consensus coordination control mechanism of multi agent systems with communication delays

Cooperative Control of Multi-Agent Systems Frank L. Lewis, Hongwei Zhang, Kristian Hengster-Movric, Abhijit Das, 2013-12-31 Cooperative Control of Multi Agent Systems extends optimal control and adaptive control design methods to multi agent systems on communication graphs It develops Riccati design techniques for general linear dynamics for cooperative state feedback design cooperative observer design and cooperative dynamic output feedback design Both continuous time and discrete time dynamical multi agent systems are treated Optimal cooperative control is introduced and neural adaptive design techniques for multi agent nonlinear systems with unknown dynamics which are rarely treated in literature are developed Results spanning systems with first second and on up to general high order nonlinear dynamics are presented Each control methodology proposed is developed by rigorous proofs All algorithms are justified by simulation examples The text is self contained and will serve as an excellent comprehensive source of information for researchers and **Adaptive Collaborative Control of Multiagent Systems by** graduate students working with multi agent systems Event-Triggered Mechanisms Juan Zhang, Huaguang Zhang, Dongsheng Yang, Yanhong Luo, Bowen Zhou, 2025-02-20 This book provides a detailed study of several types of control problems in multi agent systems including consensus output regulation containment and formation problems The research on collaborative control of multi agent systems has attracted engineers and scientists from various disciplines such as control mathematics artificial intelligence and computer engineering This book proposes a control strategy based on adaptive triggering mechanism and establishes a basic energy saving framework it also proposes an adaptive learning rate to replace fixed weights ensuring that the proposed strategy does not rely on any global information of the communication topology and has scalability This book is ideal for students researchers and engineers in collaborative control wireless networks power grids UAVs and more **Cooperative Control** of Multi-Agent Systems Jianan Wang, Chunyan Wang, Ming Xin, Zhengtao Ding, Jiayuan Shan, 2020-03-25 Cooperative Control of Multi Agent Systems An Optimal and Robust Perspective reports and encourages technology transfer in the field of cooperative control of multi agent systems The book deals with UGVs UAVs UUVs and spacecraft and more It presents an extended exposition of the authors recent work on all aspects of multi agent technology Modelling and cooperative control of multi agent systems are topics of great interest across both academia research and education and industry for real

applications and end users Graduate students and researchers from a wide spectrum of specialties in electrical mechanical or aerospace engineering fields will use this book as a key resource Helps shape the reader s understanding of optimal and robust cooperative control design techniques for multi agent systems Presents new theoretical control challenges and investigates unresolved open problems Explores future research trends in multi agent systems Offers a certain amount of analytical mathematics practical numerical procedures and actual implementations of some proposed approaches

Fixed-Time Cooperative Control of Multi-Agent Systems Zongyu Zuo, Qing-Long Han, Boda Ning, 2019-05-28 This monograph presents new theories and methods for fixed time cooperative control of multi agent systems Fundamental concepts of fixed time stability and stabilization are introduced with insightful understanding This book presents solutions for several problems of fixed time cooperative control using systematic design methods The book compares fixed time cooperative control with asymptotic cooperative control demonstrating how the former can achieve better closed loop performance and disturbance rejection properties It also discusses the differences from finite time control and shows how fixed time cooperative control can produce the faster rate of convergence and provide an explicit estimate of the settling time independent of initial conditions This monograph presents multiple applications of fixed time control schemes including to distributed optimization of multi agent systems making it useful to students researchers and engineers alike

Cooperative Control of Multi-agent Systems Guanglei Zhao, Hailong Cui, Changchun Hua, Shuang Liu, 2024-03-23 This book focuses on stability analysis and control design approaches for multi agent systems under network induced constraints A hybrid system approach is introduced to address the cooperative control problem of networked multi agent systems and several important topics such as asynchronous sampled data cooperative control hybrid event triggered cooperative control and reset based cooperative control are studied under the hybrid system framework. The special feature of this book is that a hybrid systems approach is proposed for the cooperative control of multi agent systems which is beneficial for relaxing the conservativeness of stability analysis and network parameter computation Interested readers can learn a novel approach to cooperative control of multi agent systems and this book can benefit researchers engineers and graduate students in the fields of multi robot cooperation unmanned aerial vehicle formation control engineering etc Distributed Event-triggered Control Zhongkui Li, Bin Cheng, Weihao Song, Shiqi Zhang, 2023-12-11 This book focuses on distributed event triggered control of multi agent systems in which the event triggering mechanism is utilized to reduce the communication frequencies in order to compensate for constrained network bandwidths an aspect that poses significant challenges for distributed control design The book summarizes the authors original systematic contributions on scalability and robustness two core issues in distributed event triggered control Specifically the book presents fully distributed adaptive event triggered control laws as they rely on neither continuous communications nor global information on the network these laws are scalable with regard to network size and topology Moreover the book provides novel and robust event triggered

algorithms which can accommodate various frequency domain and matching uncertainties. The results presented here are applicable to UAV swarms automobile systems aerospace systems vehicle platooning and more and will be of considerable interest to graduate students researchers and engineers working on network control systems Building a Low-Carbon Future Jiayue Sun, Meina Zhai, Shu Liu, Peng Shi, 2024-03-20 This book aims to emphasize the state of the art research in realizing the optimal synthesis of microgrid voltage regulation problems using adaptive multi agent control theory The contents of this book are divided into four parts The book describes the microgrid voltage regulation model construction Building upon this foundation the book investigates fault tolerant and event triggered control problems under different constraints The effectiveness and applicability of the design methods are verified by simulation arithmetic and applications The key features of this book are summarized as follows 1 Development of a unified modeling framework for the analysis and design of voltage regulation protocols 2 Utilization of a novel approach to analyze microgrid secondary control systems addressing various issues such as event triggering and fault tolerant control problems 3 A set of newly developed techniques e g Lyapunov stability theory LMI techniques is used to addressemerging voltage regulation challenges This book is a timely reflection of developments in the new field of integrated theory of voltage regulation and multi agent system control for microgrids It serves as a comprehensive collection of the latest research findings making it a valuable textbook for senior and graduate students who are interested in acquiring knowledge about the following 1 the latest techniques in microgrid voltage regulation 2 the latest advances in multi agent system control and 3 the latest advances in stability performance analysis tracking control fault tolerant control event triggered control and adaptive control The content of this monograph is divided into six parts 1 Part one studies the classical problems of microgrid control and multi agent control 2 Part two focuses on the event triggered fault tolerant voltage restoration problem for islanded microgrids 3 Part three addresses the fully distributed fault tolerant secondary event triggered control of microgrids under directed graphs 4 Part four examines the output feedback based fault tolerant load voltage regulation problem using intermittent communication 5 Part five presents the secondary load voltage and frequency regulation control based on hierarchical fault tolerant containment control 5 Part six investigates the distributed critical bus voltage regulation control problem for multiple microgrids with a positive minimum inter event time On Distributed and Cooperative Control Design for Networks of Dynamical Systems Georg Seyboth, 2016-06-17 This thesis contributes to the development of a cooperative control theory for homogeneous and heterogeneous multi agent systems consisting of identical and non identical dynamical agents respectively The goal is to explain fundamental effects of non identical agent dynamics on the behavior of a distributed system and primarily to develop suitable control design methods for a wide range of multi agent coordination problems Output synchronization problems as well as cooperative disturbance rejection and reference tracking problems in multi agent systems are investigated Suitable controller design methods for networks consisting of identical or non identical linear time invariant systems linear parameter

varying systems and selected classes of nonlinear systems are developed These controller design methods provide a solution to a wide variety of distributed coordination and cooperative control scenarios **Resilient Cooperative Control and** Optimization of Multi-Agent Systems Zhi Feng, Xiwang Dong, Guoqiang Hu, Jinhu Lyu, 2025-02-03 Resilient Cooperative Control and Optimization of Multi Agent Systems addresses various resilient cooperative control and optimization problems of multi agent systems that are vulnerable to physical failure and cyber attacks and consist of multiple decision making agents that interact in a shared environment to achieve common or conflicting goals Critical infrastructures such as smart grids wireless sensor network multi robot system etc are typical examples of multi agent systems that consist of the large scale physical processes which are monitored and controlled over a set of communication networks and computers Presents solutions to different resilient cooperative control and optimization problems of multi agent systems Includes a wealth of examples on attack resilient consensus control time varying formation tracking control distributed optimization and distributed Nash equilibrium game seeking Shows in detail the practicalities of how to develop an attack resilient cooperative control and optimization framework Distributed Cooperative Control of Multi-agent Systems Wenwu Yu, Guanghui Wen, Guanrong Chen, Jinde Cao, 2017-05-01 A detailed and systematic introduction to the distributed cooperative control of multi agent systems from a theoretical network perspective Features detailed analysis and discussions on the distributed cooperative control and dynamics of multi agent systems Covers comprehensively first order second order and higher order systems swarming and flocking behaviors Provides a broad theoretical framework for understanding the fundamentals of distributed cooperative control Cooperative Control of Complex Network Systems with Dynamic Topologies Guanghui Wen, Wenwu Yu, Yuezu Lv, Peijun Wang, 2021-07-01 Far from being separate entities many social and engineering systems can be considered as complex network systems CNSs associated with closely linked interactions with neighbouring entities such as the Internet and power grids Roughly speaking a CNS refers to a networking system consisting of lots of interactional individuals exhibiting fascinating collective behaviour that cannot always be anticipated from the inherent properties of the individuals themselves As one of the most fundamental examples of cooperative behaviour consensus within CNSs or the synchronization of complex networks has gained considerable attention from various fields of research including systems science control theory and electrical engineering This book mainly studies consensus of CNSs with dynamics topologies unlike most existing books that have focused on consensus control and analysis for CNSs under a fixed topology As most practical networks have limited communication ability switching graphs can be used to characterize real world communication topologies leading to a wider range of practical applications This book provides some novel multiple Lyapunov functions MLFs good candidates for analysing the consensus of CNSs with directed switching topologies while each chapter provides detailed theoretical analyses according to the stability theory of switched systems Moreover numerical simulations are provided to validate the theoretical results Both professional researchers and laypeople will benefit from this

book <u>Distributed Cooperative Control of Multi-agent Systems</u> Wenwu Yu, Guanghui Wen, Guanrong Chen, Jinde Cao, 2016-10-18 A detailed and systematic introduction to the distributed cooperative control of multi agent systems from a theoretical network perspective Features detailed analysis and discussions on the distributed cooperative control and dynamics of multi agent systems Covers comprehensively first order second order and higher order systems swarming and flocking behaviors Provides a broad theoretical framework for understanding the fundamentals of distributed cooperative control Time-Varying Formation Tracking Control for Nonlinear Swarm Systems Jianglong Yu, Xiwang Dong, Zhang Ren, 2023-07-14 The book focuses on time varying formation control approaches for practical nonlinear swarm systems Time varying formation control is the basic guarantee for performing other tasks of swarm systems such as cooperative decision making and cooperative detection However most practical swarm systems have nonlinear dynamic models This book studies three typical models of practical nonlinear swarm systems which represent most of the practical systems and construct the corresponding formation control structure At the same time the effects of disturbances uncertain dynamics random noise and unknown leader's input are considered and processed to improve the robustness and adaptability. The comprehensive and systematic treatment of practical nonlinear time varying formation control issues is one of the major features of the book which is particularly suited for readers who are interested to learn time varying formation control solutions in nonlinear swarm systems The book benefits researchers engineers and graduate students in the fields of formation control nonlinear control robust control etc

The Enigmatic Realm of Cooperative Control Of Multi Agent Systems A Consensus Region Approach: Unleashing the Language is Inner Magic

In a fast-paced digital era where connections and knowledge intertwine, the enigmatic realm of language reveals its inherent magic. Its capacity to stir emotions, ignite contemplation, and catalyze profound transformations is nothing in short supply of extraordinary. Within the captivating pages of **Cooperative Control Of Multi Agent Systems A Consensus Region Approach** a literary masterpiece penned by a renowned author, readers attempt a transformative journey, unlocking the secrets and untapped potential embedded within each word. In this evaluation, we shall explore the book is core themes, assess its distinct writing style, and delve into its lasting effect on the hearts and minds of those that partake in its reading experience.

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